



European Space Elevator Challenge 2016

Handbook – Beginners' Level

Version 1.4a

VESTNER
AUFZÜGE
ELEVATING PEOPLE

WARR e.V.
Wissenschaftliche
Arbeitsgemeinschaft
für Raketentechnik
und Raumfahrt

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1. Introduction

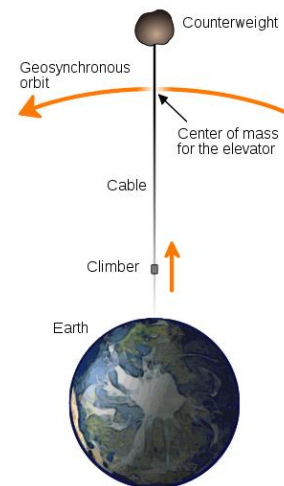
1.1. The Idea of the Space Elevator

The fundamental idea of the “space elevator” goes back to 1895, when the scientist Konstantin Tsiolkovsky considered building a tower from the surface of the Earth and reaching into the geostationary orbit. The Artsutanov paper – 1960 – proposed a way to build a tensile structure to the geostationary orbit.¹

The aim was and still is, among other objectives, to deliver payload – satellites, astronauts or other equipment – to space in an economically viable way. This idea could be an alternative solution to the expensive use of rockets.

The actual concept of the space elevator system includes a tether reaching from the surface of the Earth to the geostationary orbit. To keep the tether taut by means of gravitational and rotational forces, the center of mass of the space elevator has to be kept above this orbit. A climber is attached to the tether, which carries the payload up to the space station or to the satellite.

The energy supply is planned to be realized by “power beaming” (such as laser), as well as using solar cells.



1.2. European Space Elevator Challenge

The challenge is to design and build a climber structure in compliance with predetermined requirements, keeping in mind the idea of a real space elevator.

Our focus is on:

- the efficiency of the climber
- the technical implementation of the climber (especially payload systems)
- aspects which directly impact the development of the “real” space elevator system

The objectives of the European Space Elevator Challenge are:

- to inspire young engineers and scientists – especially in Europe – for the idea of the Space Elevator and to establish a bigger Space Elevator community in Europe
- to share experience and improve the understanding of the Space Elevator system
- to introduce the Space Elevator to a wider public
- to provide an opportunity for students to apply their theoretical knowledge in practice
- to excite high school students for science, technology and space travel

These aims are considered as long-term goals and cannot be accomplished with one competition. Hence, our goal is to organize the European Space Elevator Challenge annually.

¹ http://images.spaceref.com/docs/spaceelevator/Artsutanov_Pravda_SE.pdf

1.3. The Organizers



WARR

Scientific Workgroup for
Rocketry and Space Flight

The European Space Elevator Challenge is organized by WARR e.V., the Scientific Workgroup for Rocketry and Spaceflight at Technical University of Munich (TUM). It is directly affiliated with the Institute of Astronautics (Irt).

WARR was founded in 1962 and is one of the oldest scientific workgroups of TUM. The aim of WARR is to provide its members with the opportunity to accomplish scientific work and gain experience in practical projects as an addition to their studies. Its over 100 student members are organized in multiple groups, working on different topics such as hybrid rocket engines, cubesats, the Hyperloop and space elevators.

1.4. The Main Sponsor



VESTNER Aufzüge is an independent, medium-sized enterprise based in Munich operating throughout Europe. 80 years of experience in elevator construction have given them a high degree of flexibility in terms of technology, design and processing. They are able to respond quickly to the call for new and innovative technologies in its future-oriented products at all times.

VESTNER Aufzüge is proud to support the European Space Elevator Challenge as the main sponsor this year and wishes all participants great success!

2. Participation

2.1. Levels

For the 2016 challenge, teams can take part in one of two different levels, according to their experience and scientific background:

- The Beginners' Level is aimed at high school teams and first time participants with limited experience in the design of technical systems.
- The Advanced Level is aimed at university teams with advanced knowledge in CAD and electronics design.

This document describes the rules and requirements for the Beginners' Level. For the Advanced Level, please refer to the respective document in the Download section of the EUSPEC website.

2.2. Eligibility

There are no restrictions on who can enter the competition and form a team. Team members can be of any age, nationality, education level or profession. However, at least one member (the team leader) must be 18 years or older. In case of school teams, this can be a teacher or similar person. The number of team members is not limited (and can even be just one person).

To be eligible to participate, a team must apply via the EUSPEC website until the stated application deadline. Only in special cases will teams be allowed to enter the competition if this deadline was missed.

We reserve the right to reject a team application in case the number of applications exceeds the capacity of the event or for any other valid reason.

2.3. Registration Fee

There is no registration fee for the 2016 challenge. There will only be a small fee per person to cover costs for food and drinks, collected on the first day of the competition.

Teams will have to cover costs for travel and accommodation themselves. We suggest to try to find funding through your institution, educational foundations or corporate sponsors.

2.4. Application Flow

STEP 1 EXTENDED UNTIL MAY 31ST, 2016

The team must register for the competition through the online application form. At this point, the level of participation must be chosen and only the team leader must be named. He or she must be 18 years or older.

The team will receive a confirmation of application if the application information was complete. The confirmation of participation is with reservation of step 2.

After May 31st and until June 30th, applications will still be accepted if the rough climber concept is handed in together with the application.

STEP 2 UNTIL JUNE 30TH, 2016

The team must send in a rough concept of their climber, including estimates on parameters such as mass, size and power requirements.

After this, the team will receive a confirmation of participation if the rough concept gives reason to expect a successful participation in the competition.

A contact person from our organization team will be allocated to the team. He/she serves as a point of contact between the team and the organizers in case of any questions, problems or complaints.

STEP 3 UNTIL AUGUST 31ST, 2016

The team must send in a short video demonstrating a working climber on a rope or tether. Otherwise, the confirmation of participation can be revoked. The team must also send in a full list of all team members and a list of the team members present at the competition.

STEP 4 UNTIL SEPTEMBER 12TH, 2016

The team must hand in a poster about the team, the climber and the development process. More information on this can be found in the next chapter. Also, the Authorization to Release Information Form must be signed and handed in (see Section 9.1).

3. Poster

Each team has to prepare a poster for the competition. This poster should mainly act as an introduction of your team and your climber to the guests and visitors as well as to the press and the other teams on the days of the European Space Elevator Challenge.

3.1. Properties

- Language: English
- Format: ISO 216 A1 (vgl. DIN A1)

3.2. Content

The poster may contain amongst other things:

- The name of your team
- A picture of your team
- Where your team is from (nationality, institution)
- A picture of your climber
- The specifications of your climber
- Notable aspects of your climber

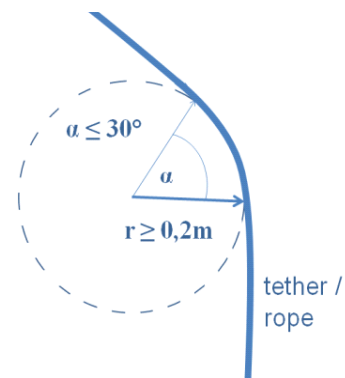
3.3. Structure

The structure of the poster is up to you. It is advisable to use pictures and charts in order to make your poster more descriptive and colourful. Please pay attention to use a large enough size of your pictures. Please choose the font and the size of your text so that it can be read easily by the viewer.

4. Climber Requirements

4.1. Structure

- The climber has to be designed to operate either on a flat tether or a round rope (see Section 5.1 for the respective specifications).
- The climber must not weigh more than 10 kg.
- The dimensions of the climber must not exceed 0,5 m x 0,5 m x 1 m (length, width, height). The height is defined as the dimension along the tether/rope.
- The climber structure can be made from any material including LEGO® or fischertechnik®, but also steel, aluminium or carbon fiber.
- When attached to the tether/rope, the center of gravity of the climber along the horizontal should be close to the tether/rope.
- The climber must not bend the tether/rope with a radius of less than 0.2 m and an angle larger than 30° (see drawing). An enlargement of the tether/rope must be avoided.²
- The climber must not contain any elements with positive buoyancy or that have aerodynamic lifting surfaces.
- The climber must neither damage the tether/rope nor degrade its properties nor leave any material on it.
- The climber must be designed in such a way that it can be mounted on and dismantled from the tether/rope without a disassembly of the latter.



4.2. Power

- The climber power has to be provided by batteries only.
- Batteries are **not** provided by the organization team. Each team must bring their own.

4.3. Electronics

- The climber has to operate autonomously during the whole drive.
 - For starting the drive at the very beginning a non-autonomous mechanism is permitted to be used.
 - The climber must be able to start its drive without any external force acting on it (no pushing etc.).
 - After the start of the drive on the tether/rope, the climber must stop on the top of the tether/rope – after covering the distance of 20 m – and restart to go down by operating exclusively autonomously.
- The climber has to be equipped with sensors which detect the end of the climb. You may use amongst others:
 - Optical sensors. The tether/rope has black-on-white or white-on-black markings indicating the beginning and the end of the climb.
 - Mechanical sensors. There are polystyrene bumpers at both ends of the tether/rope.
 - Odometry sensors to estimate the distance traveled.
 - It is recommended to always use mechanical sensors as a backup.
- Radio frequency utilization has to follow German regulations.

² Because of the tension no bending of the tether/rope would be appreciated at a real space elevator system.

4.4. Safety

4.4.1. General

- The temperature of all surfaces must be lower than 50 °C.
- All screws and bolts have to be secured against loosening.
- The electronics and the batteries have to be attached securely to the climber structure.
- No sharp edges are allowed on the climber.
- No current-carrying components are allowed on the surface of the climber.

4.4.2. Emergency Shutdown

- An emergency shutdown to stop the climber must be present.
- It must be possible to activate this system whenever the climber is in close proximity to the ground.
- The emergency shutdown procedure has to be accessible without endangering any team members.

5. Specifications

5.1. Tether/Rope

5.1.1. Flat Tether

- Product: Güth & Wolf Aramid Fabric Tape
- Dimensions: 38 mm width, 2 mm thickness
- Material: Teijin Twaron® Aramid
- Color: beige
- Tensile strength: 32 kN

GÜTH & WOLF
BAND - UND GURTWEBEREIEN

TEIJIN

5.1.2. Round Rope

- Product: TENDON Aramid
- Dimensions: 10 mm diameter
- Materials: Aramid sheath, Polyamid core
- Color: black
- Weight: 66.4 g/m
- Tenacity: 37 kN
- Elongation (50-150 kg): 0%
- Sheat slippage: 0%

TENDON
tied to be free

6. Ground and Track Layout

6.1. Competition Area

6.1.1. General

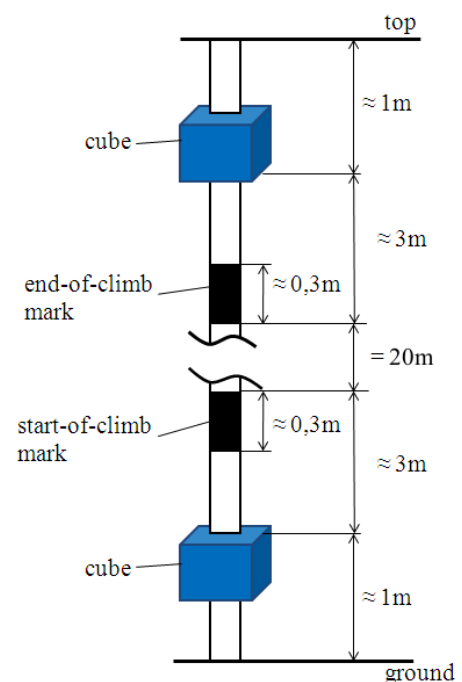
- The competition will take place at the Garching campus of the Technical University of Munich.
- The competition site consists of three main areas:
 - The team area, where each team will get a tent with a table to prepare their climber for the competition.
 - The staging area, a special tent where teams have to prepare their climber for the drive.
 - The safety area, which is the area around the drive track.

6.1.2. The Safety Area

- The safety area consists of two parts: the outer safety area and the inner safety area.
- The outer safety area:
 - Area around the drive track marked with a circle of warning tape with a diameter of 20 m.
 - Entering this area requires a safety helmet.
 - Only the team currently mounting the climber and the organization staff of EUSPEC are allowed to enter the outer safety area.
- The inner safety area:
 - Area directly around the bottom attachment point of the tether/rope and directly beneath the tether/rope.
 - During the drive of the climber the inner safety area has to be cleared.

6.2. Drive Track

- One end of the tether/rope is attached to the ground, the other end is attached to a manlift.
- The climber-assembly-range is at about 1m above the ground.
- At the bottom and the top of the tether or rope are foamed polystyrene cubes with approximate dimensions of 0.5 m x 0.5 m x 0.5 m.
- The climber-assembly-range is 3 m between the bottom cube and the start-of-climb mark.
- The start-of-climb mark is a 0.3 m long black-on-white or white-on-black line.
- The distance between the start-of-climb and end-of-climb mark is 20 m.
- The same arrangement is on the top.
- The tether/rope will normally be within 45° from the vertical. Close to the ground and depending on the weight of the climber this value can be exceeded locally.



7. Procedures

7.1. General

- The competition is composed of consecutive time slots, distributed over two days, in which the teams will perform drives with their climber.
- There will be four time slots per team with a duration of 15 minutes each.
- Teams can decide to combine two time slots into one time slot of double length.
- A timetable showing the team order and approximate starting times will be published at the beginning of the competition days.
- Changes in the contest operation will be announced to all team leaders at once.
- Teams must clean up their workspace at the end of the day and not damage property.
- Please respect the other teams!

7.2. Pre-Drive

- The climber check-up will be held directly before the time slot.
- The climbers will be checked to ensure that they obey the rules and regulations of the competition. If not, the teams will be given time until the beginning of their next time slot to fix the issues, when they will be checked again.
- The team members have to arrive at the staging area at least 15 minutes before the beginning of their time slot.
- During the preparation time within the staging area the climber will be weighed.
- All team members will receive safety helmets and safety gloves at the staging area which are mandatory to be worn while in the safety area.
- Should any issues with regards to safety or regulatory compliance of the climber arise while in the staging area, the team can be denied to drive.

7.3. Drive

- During their time slot, a team has to mount their climber to the tether/rope, climb up and down and demount their climber. Within the time slot the climber can drive up and down as many times as the team wants.
- For a drive to be valid with regards to scoring, the climber must cross both the start-of-climb mark and the end-of-climb mark with its full length while driving up and down.
- The drive downwards has to be performed in a controlled and safe manner.
- The remaining time slot time will be indicated on a widely visible digital clock.
- A team has to leave the safety area **before** the time of its time slot runs out. Otherwise it will incur a penalty (see Section 8.2).
- The organisation team has the authority to end a time slot prematurely if the rules are violated or due to bad weather conditions.
- The number of team members for mounting, dismounting and climber operation is limited to three. Additional persons need the permission of the organisation team.

7.4. Post-Drive

- The safety helmets and gloves have to be returned to the organisation team.
- Teams must pick up all their hardware from the staging area after their time slot.

7.5. Safety

As is evident from our competition design, safety is our first priority. Unsafe behavior during the event will not be tolerated. Generally, please behave in a safe and polite way.

- Within the safety area you must wear a safety helmet and safety gloves. Both will be provided by the organizers.
- The inner safety area has to be cleared immediately after starting the climber and can only be re-entered when the climber is at a standstill in the bottom climber-assembly-range.
- You are responsible for your team's tent. Try to keep it clean and organized. Do not leave any tools unnecessarily lying around. Minimize any possible exposure to current carrying components, sharp edges or moving parts.
- Always turn off your climber and any electrical tools when leaving your tent.
- Keep in mind the safety of potential visitors or jury members, especially when leaving your tent.
- If you use electrical devices at the competition area or the TU Munich keep in mind the specifications of the European power grid (230 V, 50 Hz).
- The emergency numbers are **112** or **+49 89 289 112** for mobile phones.

8. Evaluation

8.1. Scoring

The teams will receive scores in the three categories “speed”, “weight” and “construction quality”.

- The score in the category “speed” is based on the fastest upward climb of a team. The time measurement is done by the organization team. This is the only valid time measurement for the scoring.
- The score in the category “weight” is based on the weight measurements right before the time slots. Lower weight means higher score.
- The score in the category “construction quality” is based on a jury assessment during the competition days. Please be prepared that the jury members will visit you at your tent to examine your climber. Well thought out and well executed designs will receive a high rank.

Every team will be given a score on a (linear) scale from 0 to 100 in each category. In the categories “speed” 0 points represents a track time of 5 minutes or more and 100 points a time of 0 minutes. In the category “weight” 0 represents a weight of 5 kg or more and 100 a weight of 0 kg. The overall winner is the team with the highest sum of scores from all three categories.

8.2. Penalties

- If the climber does not fulfill the requirements of the rulebook, the team will not be allowed to participate until all issues are resolved.
- If the team exceeds its time slot time, the time measurements of all climbs within this slot will be increased by 25%.
- Not obeying the safety procedures will result in a warning (yellow card) and, if continued, in a cancellation of the current time slot (red card).
- Grave disobedience of the rules or unsportsmanlike behavior will result in immediate disqualification from the competition.

8.3. Complaints

- If a team feels that a judgment is flawed, it can file a complaint. Complaints are accepted only on the date of competition or before it but in no cases afterwards.
- For complaints during the competition or before, the team shall contact the respective team contact person.

9. Additional Information

9.1. Authorization to Release Information Form

The Authorization to Release Information form allows us to avoid legal trouble when publishing any information or media generated during the event. Each team member must sign the form and hand it in until the deadline. To do this, please download the blank form from the EUSPEC website.

DEADLINE: SEPTEMBER 12TH, 2016

9.2. Media

- All published material in conjunction with the European Space Elevator Challenge must be approved by the organizers.
- During the competition, each team must cooperate with the media partners present. This includes complying with the preparation of materials (e.g. posters) as well as responding appropriately when interacting with the media.

9.3. Changes

No liability will be accepted in result of any changes, errors and omissions in this handbook. Every team has the responsibility to ensure that they have the most recent version of this handbook from the EUSPEC website.

9.4. Contact Information

Address: WARR e.V. Space Elevator
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85748 Garching b. München
Germany

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Website: <http://euspec.warr.de/>

10. Acknowledgements

10.1. Partners

We would like to thank the following partners for making the event possible:



Department of Mechanical Engineering
Technical University of Munich



Deutsche Gesellschaft
für Luft- und Raumfahrt
Lilienthal-Oberth e.V.



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